**DEPARTMENT OF ELECTRICAL ENGINEERING**

Specialization (Power Electronics and Electrical Drives)

Written Test Syllabus for the PhD Admission

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| Section 1: Engineering Mathematics |
| Linear Algebra: Matrix Algebra, Systems of linear equations, Eigenvalues, Eigenvectors. Calculus: Mean value theorems, Theorems of integral calculus, Evaluation of definite and improper integrals, Partial Derivatives, Maxima and minima, Multiple integrals, Fourier series, Vector identities, Directional derivatives, Line integral, Surface integral, Volume integral, Stokes’s theorem, Gauss’s theorem, Divergence theorem, Green’s theorem. Differential equations: First order equations (linear and nonlinear), Higher order linear differential equations with constant coefficients, Method of variation of parameters, Cauchy’s equation, Euler’s equation, Initial and boundary value problems, Partial Differential Equations, Method of separation of variables.Complex variables: Analytic functions, Cauchy’s integral theorem, Cauchy’s integral formula, Taylor series, Laurent series, Residue theorem, Solution integrals. Probability and Statistics: Sampling theorems, Conditional probability, Mean, Median, Mode, Standard Deviation, Random variables, Discrete and Continuous distributions, Poisson distribution, Normal distribution, Binomial distribution, Correlation analysis, Regression analysis. |
| Section 2: Electric circuits |
| Network elements: ideal voltage and current sources, dependent sources, R, L, C, M elements; Network solution methods: KCL, KVL, Node and Mesh analysis; Network Theorems: Thevenin’s, Norton’s, Superposition and Maximum Power Transfer theorem; Transient response of dc and ac networks, sinusoidal steady-state analysis, resonance, two port networks, balanced three phase circuits, star-delta transformation, complex power and power factor in ac circuits. |
| Section 3: Electromagnetic Fields |
| Coulomb's Law, Electric Field Intensity, Electric Flux Density, Gauss's Law, Divergence, Electric field and potential due to point, line, plane and spherical charge distributions, Effect of dielectric medium, Capacitance of simple configurations, Biot-Savart’s law, Ampere’s law,Curl, Faraday’s law, Lorentz force, Inductance, Magnetomotive force, Reluctance, Magnetic circuits, Self and Mutual inductance of simple configurations. |
| Section 4: Signals and Systems |
| Representation of continuous and discrete time signals, shifting and scaling properties, linear time invariant and causal systems, Fourier series representation of continuous and discrete time periodic signals, sampling theorem, Applications of Fourier Transform for continuous and discrete time signals, Laplace Transform and Z transform. R.M.S. value, average value calculation for any general periodic waveform |
| Section 5: Electrical Machines |
| Single phase transformer: equivalent circuit, phasor diagram, open circuit and short circuit tests, regulation and efficiency; Three-phase transformers: connections, vector groups, parallel operation; Auto-transformer, Electromechanical energy conversion principles; DC machines: separately excited, series and shunt, motoring and generating mode of operation and their characteristics, speed control of dc motors; Three-phase induction machines: principle of operation, types, performance, torque-speed characteristics, no-load and blocked-rotor tests, equivalent circuit, starting and speed control; Operating principle of single-phase induction motors; Synchronous machines: cylindrical and salient pole machines, performance and characteristics, regulation and parallel operation of generators, starting of synchronous motors; Types of losses and efficiency calculations of electric machines |
| Section 6: Power Systems |
| Basic concepts of electrical power generation, ac and dc transmission concepts, Modelsand performance of transmission lines and cables, Series and shunt compensation, Distribution systems, Per-unit quantities, Bus admittance matrix, Gauss- Seidel and Newton-Raphson load flow methods, Voltage and Frequency control, Power factor correction, Symmetrical components, Symmetrical and unsymmetrical fault analysis, System stability concepts, Equal area criterion. |
| Section 7: Control Systems |
| Mathematical modeling and representation of systems, Feedback principle, transfer function, Block diagrams and Signal flow graphs, Transient and Steady-state analysis of linear time invariant systems, Stability analysis using Routh-Hurwitz and Nyquist criteria, Bode plots, Root loci, Lag, Lead and Lead-Lag compensators; P, PI and PID controllers; State space model, Solution of state equations of LTI systems |
| Section 8: Electrical and Electronic Measurements |
| Bridges and Potentiometers, Measurement of voltage, current, power, energy and power factor; Instrument transformers, Digital voltmeters and multimeters, Phase, Time and Frequency measurement; Oscilloscopes, Error analysis. |
| Section 9: Analog and Digital Electronics |
| Simple diode circuits: clipping, clamping, rectifiers; Amplifiers: biasing, equivalent circuit and frequency response; oscillators and feedback amplifiers; operational amplifiers: characteristics and applications; single stage active filters, Active Filters: Sallen Key, Butterwoth, VCOs and timers, combinatorial and sequential logic circuits, multiplexers, demultiplexers, Schmitt triggers, sample and hold circuits, A/D and D/A converters. |
| Section 10: Power Electronics and Electrical Drives |
| Static V-I characteristics and firing/gating circuits for Thyristor, MOSFET, IGBT; DC to DC conversion: Buck, Boost and Buck-Boost Converters; Single and three-phase configuration of uncontrolled rectifiers; Voltage and Current commutated Thyristor based converters; Bidirectional ac to dc voltage source converters; Magnitude and Phase of line current harmonics for uncontrolled and thyristor based converters; Power factor and Distortion Factor of ac to dc converters; Single-phase and three-phase voltage and current source inverters, sinusoidal pulse width modulation.Power converters for IM, effect of Harmonics, voltage and current fed induction motor drives, slip power recovery, scalar and vector control, sensor-less vector control: speed estimation techniques, Direct torque and flux control, adoptive control, Application.Sinusoidal SPM machine drives, synchronous reluctance machine drives, Sinusoidal IPM machine drives, Trapezoidal SPM machine drive, wound field synchronous motor drive, Load-commutated Synchronous Motor Drives, Model of PMSM, sensor less control. |